Nonlocal Effect on Buckling of Triangular Nano-composite Plates

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ABSTRACT

In the present study, small scale effect on critical buckling loads of triangular nano-composite plates under uniform in-plane compression is studied. Since at nano-scale the structure of the plate is discrete and the long-range cohesive forces become important, the size-dependent nonlocal elasticity theory is employed to develop an equivalent continuum plate model for this nanostructure incorporating the change in its mechanical behavior. Two parameter Winkler-Pasternak elastic medium is used to precisely model the elastic behavior of the matrix surrounding the nano-plate. The governing stability equations are then derived using the classical plate theory and the principle of virtual work for a perfect uniform triangular nano-plate composite system. The well-known numerical Galerkin method is then used as the basis for the solution in conjunction with the areal coordinates system. The solution procedure views the entire nano-composite plate as a single super element which can be of general shape. Effects of nonlocal parameter, length, aspect ratio, mode number, anisotropy, edge supports and elastic medium on buckling loads are investigated. All of these parameters are seen to have significant effect on the stability characteristics of nano-composite plate. It is shown that the results depend obviously on the non-locality of buckled nano-composite plate, especially at very small dimensions, small aspect ratios, higher mode numbers, higher anisotropy and stiffer edge supports. Also it is seen that the medium parameters, especially the Winkler parameter, have significant influence on the small scale effect and can decrease or increase it. Also, it is seen that the classical continuum mechanics overestimates the results which can lead to deficient design and analysis of these widely used nanostructures. The results from current study can be used in design, analysis and optimization of different nano-devices such as nano-electro-mechanical systems (NEMS) utilizing nano-composite plates as load-bearing components. Although it is seen that nano-fillers, here the nano-plates, increase the stiffness of the whole nano-composite, by increasing the bending rigidities, on the other hand it is shown in this study that the small scale effect or the nonlocal effect decreases the critical loads of the nano-plates. Thus, the nonlocal effect plays a key role in the design of these nanostructures and must be attended and comprehensively studied to avoid the failure of the nanostructure. Further, the solution employed here is general and can be applied to nano-composite plates with arbitrary shapes which is an asset in structural optimization.

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NOMENCLATURE

\( L_1, L_2, L_3 \) the areal coordinates
\( A_1, A_2, A_3 \) the area of the sub-triangles
\( a, b \) base side length and height of the triangular nano-plate
\( m_0 \) mass per unit area of the nano-plate
\( C \) buckling matrix
\( D_\varepsilon \) bending rigidities
\( [M] \) mass matrix
\( N_{xx}, N_{yy}, N_{xy} \) stress resultants
\( \Phi \) trial functions
\( \sigma^{(1)}_y \) components of local stress tensor
\( \sigma^{(m)}_y \) components of nonlocal stress tensor
\( q_0 \) transverse distributed pressure
\( u, v, w \) displacement fields

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1. INTRODUCTION

Outstanding physical and chemical properties of nanostructures cause their wide usage in different nano-engineering systems such as nano-sensors [1], nano-actuators [2] and nano-composites [3, 4]. Among the nano-structures, the carbon nano-tubes (CNTs) and the Graphene sheets (GSs) are being vastly used in different nano-electro-mechanical systems (NEMS) and nano-composites due to their superior mechanical and electrical properties such as strength and conductivity [3-5]. Based on this, a wide range of experimental, computational and theoretical studies have been conducted on such nano-structures to comprehensively reveal their physical properties for better design and application. Among these methods, the experimental measurements, at nano scale, are hard to reproduce and depend on the development of devices for manipulation of nano-sized objects. Also, computational techniques based on semi-empirical approaches such as ab-initio [6], molecular dynamics (MD) simulation [7], density functional theory (DFT) [8], etc., which produce results in line with the experiment, are restricted by the amount of computational capacities needed for the calculations especially when the number of atoms and bonds included in the nanostructure increases. In this way, developing an appropriate theoretical model for analyzing nanostructures eliminates the difficulties associated with the previous mentioned methods while it can also produce results in agreement with them. On this basis, continuum modeling of nanostructures is being the focus of interest [9-13]. An accurate continuum model of nanostructures must take the account of change in the material and physical properties of these structures arising at the nano scale. In fact, as the dimensions of a system reduce to the nano scale, they become comparable to the inter-atomic or inter-molecular spacing of that system and the material system can no longer be modeled as a continuum. Moreover, at nano scale, the influence of long-range inter-atomic and inter-molecular cohesive forces on the static and dynamic responses tends to be significant. These effects are referred to as the “Size” or “Small scale” effects [14-16]. Since the size independent classical continuum models are unable to capture the small scale effects, the modified continuum theories have been developed to take the account of these effects on the physical behavior of the nanostructures. Modified continuum models have the computational efficiency of the classical continuum models and at the same time produce comparable results to the experimental and semi-empirical ones. These models can be effectively used to simulate very small to very large systems. Some of the size dependent continuum theories are surface elasticity theory [17], strain gradient theory [18], couple stress theory [19] and the nonlocal elasticity theory introduced by Eringen [20, 21]. Among these theories, the nonlocal elasticity theory is seen to produce well-matched results with those from lattice, atomistic and molecular dynamics simulations [20-24]. In classical (local) continuum theory, it is assumed that stress state at a point in the continuum body depends uniquely on the strains at that point but in the nonlocal elasticity theory, it is assumed that stress state at a point depends not only on strains in that point but also on the strains at all other points of the continuum body especially on those which are in the effective neighboring domains [20, 21].

In fact, as one of the dimensions of the structure reduces to nanometer and becomes comparable to its molecular or atomic bond lengths, the small scale effects, which cause change in the physical properties, including the mechanical properties of the material, become prominent. These changes are due to the discreteness of the structures at this scale and the effect of the long-range intermolecular and interatomic cohesive forces which act on the atoms in the point under stress study from adjacent atoms or a few internal characteristic lengths further. These long-range cohesive forces induce a nonlocal effect which is captured through a cut-off function in the nonlocal continuum theory. The nonlocal elasticity theory first was used for stress analysis in crack tips and screw dislocations [20, 21]. It includes a small length scale parameter or nonlocal parameter which is obtained from matching the dispersion curves with those from lattice dynamic or atomistic/molecular simulations [20-24]. According to the Eringen [21] and other researchers using nonlocal elasticity theory [22-42], the nonlocal parameter depends on the material structure and physics of the problem under investigation e.g. loading, boundary conditions, etc.
Buckling analysis of nano scaled structures is an important issue for proper design and use of them in different nano-systems as load bearing components. There are numerous studies on the use of modified nonlocal continuum models for buckling and vibration analysis of nano-structures such as carbon nano-tubes [25], nano-beams [26], nano-rings/arches [27] and nano-plates [28-36, 43]. Among these nano-structures, nano-tubes such as CNTs and plate-like nano-structures such as GSs are widely used as reinforcement in nano-composites because of their strength and conductivity [3-5]. Different studies considering the nonlocal continuum modeling of nano-composites with such reinforcements have been conducted to examine and calibrate their buckling and vibration characteristics [28-36, 44]. In all of these studies the Eringen nonlocal elasticity theory is suggested for accurate prediction of dynamic response of equivalent continuum models of nano-plate reinforced composites and the classical theory is seen to overestimates the buckling loads.

In almost all of the studies conducted on the analysis of nano-composite plates, the shape of nano-plate has received the less attention. In this case, Duan and Wang [38] reported exact solution for axisymmetric bending of circular Graphene sheets based on the nonlocal elasticity theory. Farajpour et al. [39] reported axisymmetric buckling of circular Graphene sheets using nonlocal continuum plate model. Babaie and Shahidi [40] studied small scale effects on the buckling of quadrilateral nano plates using the Galerkin method. Malekzadeh et al. [41] investigated thermal buckling of orthotropic arbitrary straight-sided quadrilateral nano-plates using the nonlocal classical plate theory (NCPT). Anjomshoa [42] studied the buckling of elliptical nano-plates using the Ritz functions and nonlocal continuum mechanics. Ravari and Shahidi [43] also reported the buckling of annular nano-plates via finite difference method. Since the synthesis of nano-plates with controlled size and morphology is a challenging issue, a comprehensive and detailed study on the analysis of nano-plates with different shapes should be conducted to examine the load bearing capacity of these widely used nano-structures. One of these nano-plates is the triangular nano-plate which has special application in nano-engineering systems [44, 45] and can also be used as reinforcement in nano-composites. It is obvious that the exact buckling solutions are only possible for few plates with simple shapes like rectangular or circular plates under certain boundary and loading conditions. For buckling analysis of plates with arbitrary shapes, numerical methods such as finite difference method [43], finite strip method [46], differential quadrature method (DQM) [47] and Galerkin method [48-52] are usually used in the solution procedure. The Galerkin method is a well-known mesh-free numerical approximate method which is very simple to be used and manipulated for solving different kinds of plate problem from static to dynamic [48] and linear to nonlinear [49]. These include bending [50] buckling [51] and vibration [52] of plates with arbitrary shapes. In the present work, an orthotropic nonlocal continuum model based on the classical plate theory (CPT) is developed for stability analysis of triangular nano-composite plates under uniform in-plane compression. The matrix of the composite is modeled using two-parameter Winkler-Pasternak elastic medium [53]. The principle of virtual work is used to derive the governing equations. The simultaneous eigenvalue equations are then solved using the Galerkin method on the basis of the polynomial trial functions. Effects of nonlocal parameter, length, aspect ratio, mode number, material property, different boundary conditions and medium parameters on buckling loads are thoroughly investigated. The novelty of the current work can be seen from multiple aspects including the study of decreasing effect of small scale effect in conjunction with the increasing effect of elastic medium on critical loads of nano-composite plate at higher buckling modes and the use of an efficient and easy handling numerical Galerkin’s method which can be simply used for the analysis of nano-plate with arbitrary shapes and boundary conditions. Thus, current study can also be employed for buckling analysis of nano-composite plates with general shapes which makes it referable for imperfect nanostructures analysis and the structural topology optimization problem. To the best of authors’ knowledge, the buckling of triangular nano-composite plates based on the nonlocal elasticity theory has not been reported in available literature.

Figure 1. Mapping from Cartesian coordinate system to areal coordinate system.

2. FORMULATION

2.1. Geometric Definitions

An arbitrary triangle in the Cartesian coordinates (x,y) can be mapped to a right-angled triangle in the areal coordinates (L₁, L₂) with the boundary equations being as \( L₁=0 \), \( L₂=0 \) and \( L₁+L₂ =1 \) as shown in Figure 1. The areal coordinates (\( L₁, L₂, L₃ \)) of the point P are defined as:

\[
L₁ = \frac{A₁}{A}, \quad L₂ = \frac{A₂}{A}, \quad L₃ = \frac{A₃}{A}
\]  

(1)

where \( A₁, A₂ \), and \( A₃ \) denote the areas of the sub-triangles shown in Figure 1 and \( A \) is the area of the base triangle.
The three areal coordinates are related to each other by the following expression:

\[ L_i = L_1 + L_2 + L_3 = 1 \]  

(2)

also, Cartesian and areal coordinates are related by the following relations:

\[ x(L_i, L_j) = \sum_{i=1}^{3} x_i L_i \]  

(3.1)

\[ y(L_i, L_j) = \sum_{i=1}^{3} y_i L_i \]  

(3.2)

where, \( x_i \) and \( y_i \) are the coordinates of vertices. Using Equations (3.1) and (3.2), the first-order and second-order derivatives, based on the areal coordinates, can be respectively expressed as:

\[
\begin{pmatrix}
\frac{\partial}{\partial x} \\
\frac{\partial}{\partial y}
\end{pmatrix} = [J_{11}]^{-1}
\begin{pmatrix}
\frac{\partial}{\partial L_1} \\
\frac{\partial}{\partial L_2}
\end{pmatrix}
\]  

(4.1)

\[
\begin{pmatrix}
\frac{\partial^2}{\partial x^2} \\
\frac{\partial^2}{\partial y^2} \\
\frac{\partial^2}{\partial x \partial y}
\end{pmatrix} = [J_{22}]^{-1}
\begin{pmatrix}
\frac{\partial^2}{\partial L_1^2} \\
\frac{\partial^2}{\partial L_2^2} \\
\frac{\partial^2}{\partial L_1 \partial L_2}
\end{pmatrix}
\]  

(4.2)

where, \([J_{11}], [J_{21}] \) and \([J_{22}]\) are the mapping matrices defined as:

\[
[J_{11}] =
\begin{bmatrix}
\frac{\partial x}{\partial L_1} & \frac{\partial y}{\partial L_1} \\
\frac{\partial x}{\partial L_2} & \frac{\partial y}{\partial L_2}
\end{bmatrix}
\]  

(5.1)

\[
[J_{22}] =
\begin{bmatrix}
\frac{\partial^2 x}{\partial L_1^2} & \frac{\partial^2 y}{\partial L_1^2} & \frac{\partial^2 x}{\partial L_1 \partial L_2} & \frac{\partial^2 y}{\partial L_1 \partial L_2} \\
\frac{\partial^2 x}{\partial L_2^2} & \frac{\partial^2 y}{\partial L_2^2} & \frac{\partial^2 x}{\partial L_2 \partial L_1} & \frac{\partial^2 y}{\partial L_2 \partial L_1}
\end{bmatrix}
\]  

(5.2)

\[
[J_{21}] =
\begin{bmatrix}
\frac{\partial^2 x}{\partial L_1 \partial L_2} & \frac{\partial^2 y}{\partial L_1 \partial L_2} & \frac{\partial^2 x}{\partial L_1 \partial L_2} & \frac{\partial^2 y}{\partial L_1 \partial L_2}
\end{bmatrix}
\]  

(5.3)

### 2.2. Nonlocal Classical Plate Theory

Discrete and nonlocal continuum models of a typical triangular nano-composite plate, here the Graphene based nano-composite, under uniform in-plane compression are shown in Figure 2. Cartesian coordinate system is chosen for deriving the governing equations with its origin being fixed at the center of the mid-plane. The displacement fields at the time \( t \) according to classical plate theory (CPT) are written as:

\[
u(x, y, t) = v_0(x, y, t) - zw_x(x, y, t),\]

\[
u(x, y, t) = v_0(x, y, t) - zw_y(x, y, t),\]

\[w(x, y, t) = w(x, y, t)\]  

(6)

Figure 2. Triangular nano-composite plate under in-plane uniform compression: (a) discrete model; (b) continuum model; (c) two-parameter model of elastic medium.

Here, \( u_0, v_0 \) and \( w \) denote displacement of the point \((x, y, 0)\) along \( x, \ y \) and \( z \) directions, respectively. The strain components are then obtained as:
\(e_{ix} = u_{0x} - z w_{x}, \quad e_{iy} = v_{0y} - z w_{y},\)
\(e_{iz} = \frac{1}{2} (u_{0x} + u_{0z} - 2z w_{x},\)
\(e_{ic} = e_{ic} = e_{ic} = 0.\)

(7)

According to Eringen [20, 21], the nonlocal behavior of a Hookean solid can be introduced by the following differential constitutive equations:

\[\sigma^{(n)} - \alpha \nabla^2 \sigma^{(n)} = \sigma^{(n)} = \text{St},\]

(8)

Here, \(\nabla^2 = (\bullet)_{xx} + (\bullet)_{yy}\) is the Laplacian operator in two dimensional Cartesian coordinate system. Also, \(\sigma^{(n)}, \sigma^{(nl)}, S\) and \(\varepsilon\) are, respectively, the local stress tensor, the nonlocal stress tensor, the elasticity tensor and the strain tensor, defined as:

\[\sigma^{(n)} = \begin{bmatrix} \sigma_{xx}^{(n)} & 0 & \sigma_{xz}^{(n)} \\ 0 & \sigma_{yy}^{(n)} & 0 \\ \sigma_{xz}^{(n)} & 0 & \sigma_{zz}^{(n)} \end{bmatrix}, \quad \sigma^{(nl)} = \begin{bmatrix} \sigma_{xx}^{(nl)} & 0 & \sigma_{xz}^{(nl)} \\ 0 & \sigma_{yy}^{(nl)} & 0 \\ \sigma_{xz}^{(nl)} & 0 & \sigma_{zz}^{(nl)} \end{bmatrix},
\]

\[S = \begin{bmatrix} E_x \varepsilon_{xx} & -E_x \varepsilon_{xz} & 0 \\ -E_x \varepsilon_{xz} & E_y \varepsilon_{yy} & 0 \\ 0 & 0 & G_y \varepsilon_{yy} \end{bmatrix}, \quad \varepsilon = \begin{bmatrix} \varepsilon_{xx} \\ \varepsilon_{yy} \\ 2 \varepsilon_{xy} \end{bmatrix}.\]

(9)

In Equation (8), \(\alpha\) represents the small scale parameter which depends on a characteristic length ratio \(l/l_0\) in which \(l_0\) is an internal characteristic length which can be lattice parameter, size of grain, granular distance or distance between C-C bonds in carbon nano-structures such as CNTs and GSs and \(l\) is an external characteristic length which can be wavelength, crack length or one of the dimensions of the nanostructure. The parameter \(e_0\) is a material constant related to the structure of the nano-plate and should be determined for each material independently from matching nonlocal continuum results with atomistic ones. It is obvious that Equation (8) for \(\alpha=0\) yields the well-known classical constitutive equations of the elastic solids. Based on Equation (9), the following stress and moment resultants can be defined:

\[N = \int_N \sigma^{(n)} d\zeta, \quad M = \int_N \sigma^{(n)} d\zeta,\]

\[\left[ \begin{array}{c} N_{xx} \\ N_{yy} \\ N_{xy} \end{array} \right], \quad \left[ \begin{array}{c} M_{xx} \\ M_{yy} \\ M_{xy} \end{array} \right] = \left[ \begin{array}{c} E_x \varepsilon_{xx} \\ E_y \varepsilon_{yy} \\ G_y \varepsilon_{xy} \end{array} \right].\]

(10)

where, \(\frac{h}{2}\) denotes the nano-plate’s thickness. According to Equation (8), the nonlocal effect enters through the constitutive relations. Since, the principle of virtual work is independent of the constitutive relations it can be employed to derive the equilibrium equations for the current nonlocal plate model. After applying this principle the equations of motion are obtained as [31]:

\[N_{xx,x} + N_{xy,y} = m_0 \ddot{u},\]

(11.1)

\[N_{yy,x} + N_{xy,y} = m_0 \ddot{v},\]

(11.2)

\[M_{xx,x} + 2M_{xy,y} + M_{yy,y} = \left( N_{xx,w} w_x \right)_x + \left( N_{xy,w} w_y \right)_y + \left( N_{yy,w} w_{yy} \right)_y + q_0 - m_0 \ddot{w} + m_2 \left( \ddot{w}_x + \ddot{w}_{yy} \right) = 0,\]

(11.3)

here, \(m_0\) and \(m_2\) are, respectively, mass per unit of area and mass moment of inertia of the nano-plate defined as:

\[m_0 = \int m_0 d\zeta, \quad m_2 = \int \rho \zeta^2 d\zeta,\]

(12)

where, \(\rho\) denotes the density of nano-plate. In Equation (11.3) \(q_0\) is the external applied transverse load which here is exerted by the elastic medium and then is defined as:

\[q_0 = -k_w w_k + k_p \left( w_{xx} + w_{yy} \right),\]

(13)

where, \(k_w\) is the Winkler parameter which represents the springy effect of the elastic medium by modelling it as a series of condensed linear springs. Also, in the above equation, \(k_p\) is the Pasternak parameter of the elastic medium and represents the shear interaction between the nano-plate and the elastic medium attached to it. As it is seen in the above equation, in the current model of elastic medium, the exerted pressure on the nano-plate is proportional to the transverse deflection and curvatures of the nano-plate (linear elastic medium). Using Equations (7)-(10) and assuming the two dimensional Laplacian operation, the moment resultants can be expressed in terms of the displacement field as:

\[M - \mu \nabla^2 M = -D \kappa,\]

(14)

here \(\mu=(e_0 l_0)^2\) is the nonlocal parameter, \(D\) is the bending rigidity tensor and \(\kappa\) is the curvature vector of the nano-plate defined as:

\[D = \frac{E}{12} S, \quad \kappa = \left( w_{xx}, w_{yy}, 2w_{xy} \right)^T,\]

(15)

Using Equations (11.3), (13) and (14) and assuming the solution \(w(x, y, t)=W(x, y) \exp(\text{i} \omega t)\), the following governing equation will be obtained for the nonlocal plate model of nano-composite in terms of transverse displacement [28, 31, 41]:
\[ D_{11}W_{xx} + 2(D_{12} + 2D_{66})W_{xy} + D_{22}W_{yy} + (1 - \mu)N^2 \left( -k_{\omega}w + k_{\omega} \left( w_{xx} + w_{yy} \right) + m_{\omega} \omega^2 W_w \right. \]
\[ -m_{\omega}^2 \left( W_{xx} + W_{yy} \right) + \left( N_{,w}W_x \right)_i + \left( N_{,w}W_y \right)_i \bigg] = 0 \]

(16)

where, \( W \) denotes the deflection of the nano-plate middle surface and \( \omega \) is the natural circular frequency.

### 3. SOLUTION PROCEDURE

Applying the weighted residual method to the governing equation in Equation (17) gives:

\[ \int \left[ \int \left( W_{xx} + 2(D_{12} + 2D_{66})W_{xy} + D_{22}W_{yy} + (1 - \mu)N^2 \left( -k_{\omega}w + k_{\omega} \left( w_{xx} + w_{yy} \right) + m_{\omega} \omega^2 W_w \right. \right. \right. \]
\[ \left. \left. \left. -m_{\omega}^2 \left( W_{xx} + W_{yy} \right) + \left( N_{,w}W_x \right)_i + \left( N_{,w}W_y \right)_i \right) \right) dxdy = 0 \]

(17)

where, \( \chi \) denotes the weight function. Using the divergence theorem the following form will be reached:

\[ \int R \Pi(x,y)dxdy + \int \Lambda(x)ds = 0 \]

(18)

where, \( \Pi \) and \( \Lambda \) are given in Appendix (A.1 and A.2). Also, \( R \) is the area of the nano-plate, \( \partial R \) represents the boundary of the nano-plate and \( n_x, n_y \) are the components of the unit normal vector on the boundary of the nano-plate shown in Figure 1a. For simply supported and clamped edges, the boundary conditions are simply supported edge:

\[ W = 0, \quad \text{and} \quad M_{xx} = n_x^2 M_{xx} + 2n_x n_y M_{xy} + n_y^2 M_{yy} = 0 \]

(19)

Clamped edge:

\[ W = 0, \quad \text{and} \quad W_{,x} = n_x W_x + n_y W_y = 0 \]

(20)

An approximate solution of the problem can be obtained by assuming an expression for the transverse deflection of the mid-surface which satisfies the essential boundary condition at the edges as:

\[ W(L_x, L_y) = \sum_{i=1}^{m} \sum_{j=1}^{n} \Phi_i(L_x, L_y) \]

(21)

In which, \( \Phi_i \) are the unknown coefficients to be varied and \( \Phi_i \) are defined as:

\[ \Phi_i = \left[ L_1 L_2 L_3 \right]^T \phi_i(L_x, L_y) \]

(22)

In the above equation, \( k \) is the power of the geometrical shape equation which takes 1 and 2 for simply supported and clamped edges, respectively. On this way, Equation (21) satisfies the kinematical boundary conditions at the edges. Also, \( \phi_i \) are polynomial trial functions of the form:

\[ \phi_i(L_x, L_y) = L_1^{q_1} L_2^{q_2} \]

(23)

where:

\[ i = \frac{(q+1)(q+2)}{2} - r \]

(24)

In Equation (21), \( p \) is the degree of polynomial set which may be increased until the desired accuracy is achieved. Substituting Equation (21) into Equation (18) and using the Galerkin method assumption i.e. \( \chi = \Phi_i \), the following simultaneous linear equations for both vibration and buckling problems will be yielded:

\[ \left[ [K] - \beta_1 \omega^2 [M] - \beta_2 N_m [B] \right] [C] = [0] \]

(25)

In which, \([K], [M] \) and \([B] \), defined in Appendix A, are respectively the stiffness, mass and buckling matrices associated with the nano plate. The scalar indicators \( \beta_i \) take on \( \beta_i=1, \beta_i=0 \) for free vibration problem and \( \beta_i=1 \) for the buckling problem. For simplicity the results are presented in non-dimensional buckling load parameter as \( q_i=[N_{,w}u^2/D_{11}] \). In the case of uniform in-plane compression in Figure 2a we have:

\[ N_{w} = N_{y} = N_{z} = 0 \]

(26)

Equation (25) is a standard eigenvalue problem which can be solved for critical frequencies or buckling loads of triangular nano-composite plates with the corresponding eigenvector \( [C] \) which represents the associated vibration or buckling mode shape.

### 4. RESULTS AND DISCUSSIONS

#### 4. 1. Validation and Convergence

In order to establish the validity of the current work, buckling loads for simply supported and clamped isotropic isosceles triangular plates with Young’s modulus 1.067 GPa, Poisson’s ratio 0.3, mass density 2.3 g/cm^3 and thickness \( h=0.34 \) mm are calculated from Equation (25) and are compared in Table 1. A comparison in Table 1 shows desired agreement between the results obtained here and those reported by Wang and Liew [54]. Another convergence study is also performed in Table 2 for the nonlocal case. From Tables 1 and 2 it is found that a polynomial set of degree \( p=10 \) is sufficient for the convergence of the results and the set is used to generate all the other results presented herein.

#### 4. 2. Effect of Nonlocal Parameter, Size and Mode Number

In this section the small scale effect on critical loads of isosceles triangular nano-plate is investigated for different values of base side length, aspect ratio and mode number. The base side length of the nano-plate is varied between 5 mm and 35 mm and the range of aspect ratio is considered to increase from 1 to 3.
The nonlocal parameter is also assumed to vary between \( \mu = 0 \) nm\(^2\) and 4 nm\(^2\). Firstly, the influence of base side length and nonlocal parameter on buckling loads are illustrated by Figure 3 for \( b/a = 1 \). From this figure it is found that nonlocal critical buckling loads are smaller than the local ones (\( \mu = 0 \)). In addition, for each value of the base side length, by increasing the nonlocal parameter the buckling loads decrease. The reason is that when the nonlocal parameter increases, the small scale effects increases and this leads to a reduction in the nano-plate stiffness [31]. In fact, the nonlocal effect decreases the nano-plate buckling resistance of nano-plate by increasing the intensity of buckling matrix through the nonlocal terms in Equation (25). It is also seen in Figure 3 that by increasing the base side length, the nonlocal effect decreases and the buckling loads converge to the local ones. This implies that by increasing the external characteristic length of the nano-plate (here the base side length of nano-plate \( a \)) the small scale effect decreases while the internal characteristic length is assumed to be unchanged. This is due to the size dependency in the essence of the nonlocal elasticity theory which states that as the system becomes larger, become closer to the classical continuum size order, the nonlocal or small scale effect disappears [31, 38-42]. For better understanding the influence of the base side length and nonlocal parameter, the relative errors, in percentage form, due to neglecting the nonlocal effect for base side lengths \( a = 10 \) nm and \( a = 30 \) nm with the nonlocal parameter \( \mu = 4 \) nm\(^2\), are found to be 51.83\% and 10.68\%, respectively. It is found from these values that for large enough nanostructures the classical continuum modelling can be desirably employed instead of the more complicated nonlocal theory. Here and afterwards, the relative error is defined as \( |\text{Local result} - \text{Nonlocal result}|/|\text{Local result}| \).

To see the effect of aspect ratio, the buckling parameters are plotted in Figure 4 against the aspect ratio \( b/a \) for different nonlocal parameters. Here the base side length \( a = 10 \) nm is taken. It is found from this figure that for small aspect ratios, the difference

### Table 1. Convergence study of buckling parameter \( \lambda_b \) for local (\( \mu = 0 \)) continuum model of isosceles triangular nano-plate

<table>
<thead>
<tr>
<th>Degree of polynomial set (( p ))</th>
<th>Aspect ratio (b/a)</th>
<th>1</th>
<th>1.5</th>
<th>2</th>
<th>2.5</th>
<th>3</th>
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<td>Simply supported (SSS)</td>
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<tr>
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<td></td>
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<td>63.5646</td>
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<tr>
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<td></td>
<td>127.610</td>
<td>92.377</td>
<td>77.251</td>
<td>68.881</td>
<td>63.564</td>
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### Table 2. Convergence study of buckling parameter \( \lambda_b \) for nonlocal continuum model of isosceles triangular nano-plate (\( b/a = 2, a = 10 \) nm)

<table>
<thead>
<tr>
<th>Degree of polynomial set (( p ))</th>
<th>Nonlocal parameter (( \mu ))</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Simply supported (SSS)</td>
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<td></td>
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<td></td>
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<tr>
<td>4</td>
<td></td>
<td>27.0040</td>
<td>21.2623</td>
<td>17.5342</td>
<td>14.9184</td>
<td>12.9817</td>
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<td>Clamped (CCC)</td>
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<td>77.5437</td>
<td>43.6758</td>
<td>30.3989</td>
<td>23.3122</td>
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<tr>
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<td>77.2715</td>
<td>43.5894</td>
<td>30.3570</td>
<td>23.2876</td>
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<td>8</td>
<td></td>
<td>77.2517</td>
<td>43.5831</td>
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<td>43.5827</td>
<td>30.3537</td>
<td>23.2857</td>
<td>18.8876</td>
</tr>
</tbody>
</table>
between nonlocal and local results is more prominent. An interpretation for such result is that for a specific value of the base side length and nonlocal parameter, as the aspect ratio increases the nano-plate become larger and this leads to a decrease in the small scale effect due to the previously discussed size dependent nature of the nonlocal elasticity theory. The relative error for ratios $b/a=1$ and $b/a=3$ with $\mu=4\text{ nm}^2$ are obtained as 64.70 and 46.22%, respectively. Thus, it is concluded that the nonlocal theory should be considered for the buckling analysis of triangular nano-plate with small aspect ratios.

To study the small scale effect in different buckling modes, non-dimensional buckling loads associated with the first four mode numbers are depicted in Figure 5 for different nonlocal parameters. Here, the base side length and aspect ratio are taken as $a=10$ nm, $b/a=1.5$, respectively.

It can be seen in the figure that in all of the mode numbers as the nonlocal parameter increases the buckling parameter decreases. Further, it is revealed that the nonlocal effect is more prominent in higher mode numbers. This is also true for a circular nano-plate under uniform compression [39]. For the nonlocal parameter $\mu=4\text{ nm}^2$ the relative error due neglecting the small scale effect for the first and fourth mode numbers are obtained as 56.67% and 80.94%, respectively. The buckling loads associated with the first four modes for a right-angled triangular nano-plate are, as well, presented in Table 3. It is seen in this table that similar to isosceles triangular nano-plate (Figure 5) the buckling loads of right-angled triangular nano-plate also decrease by nonlocal parameter in all modes. The associated buckling mode shapes for the isosceles and the right-angled triangular nano-plates are presented in Figure 6 and Figure 7, respectively.

4. 3. Effect of Material Properties
An investigation is performed to account for the effect of anisotropy in the orthotropic case. For this purpose, variations of the non-dimensional critical loads for a fully simply supported isosceles triangular nano-plate with aspect ratio $b/a=1$ are plotted in Figure 8 against the anisotropy ratio $E_y/E_x$ for different nonlocal parameters. The figure shows that anisotropy has an increasing effect on the critical buckling loads and as the nonlocal parameter increases this occurs in a more nonlinear manner. Also, it can be seen that as the anisotropy ratio increases the difference between local and nonlocal results increases.
Figure 6. Buckling mode shapes of isosceles triangular nano-plate: (a) 1st mode; (b) 2nd mode; (c) 3rd mode; (d) 4th mode

Figure 7. Buckling mode shapes of right-angled triangular nano-plate: (a) 1st mode; (b) 2nd mode; (c) 3rd mode; (d) 4th mode

Figure 8. Variations of buckling parameter with anisotropy ratio for different nonlocal parameters

Table 3. Buckling parameter $\lambda_b$ in the first four buckling modes for nonlocal plate model of right-angled triangular nano-plate ($b/a=1, a=10$ nm)

<table>
<thead>
<tr>
<th>Buckling mode</th>
<th>Nonlocal parameter $\mu$</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Simply supported (SSS)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1st</td>
<td>49.3480 (49.348)</td>
<td>33.0423</td>
<td>24.8359</td>
<td>19.8949</td>
<td>16.5936</td>
<td></td>
</tr>
<tr>
<td>2nd</td>
<td>98.6994</td>
<td>49.6727</td>
<td>33.1876</td>
<td>24.9179</td>
<td>19.9474</td>
<td></td>
</tr>
<tr>
<td>4th</td>
<td>167.8318</td>
<td>62.6631</td>
<td>38.5233</td>
<td>27.8100</td>
<td>21.7588</td>
<td></td>
</tr>
<tr>
<td>Clamped (CCC)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1st</td>
<td>139.5749 (139.57)</td>
<td>58.2594</td>
<td>36.8126</td>
<td>26.9073</td>
<td>21.2023</td>
<td></td>
</tr>
<tr>
<td>2nd</td>
<td>205.5739</td>
<td>67.2747</td>
<td>40.2181</td>
<td>28.6825</td>
<td>22.2894</td>
<td></td>
</tr>
<tr>
<td>3rd</td>
<td>247.8953</td>
<td>71.2557</td>
<td>41.6078</td>
<td>29.3824</td>
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<tr>
<td>4th</td>
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<td>75.2918</td>
<td>42.9523</td>
<td>30.0466</td>
<td>23.1045</td>
<td></td>
</tr>
</tbody>
</table>

* Values in parentheses are taken from [54].
4. 4. Effect of Edge Supports  The effect of small scale on the buckling loads of an isosceles triangular nano-plate is shown in Figure 9 for different support conditions at edges. It is seen in the figure that in both fully simply supported (SSS) and fully clamped boundary conditions (CCC), as the nonlocal parameter increases the buckling load parameter decreases. Further, it is found that the nonlocal effect is more prominent for clamped boundary condition. The relative error percent due to neglecting nonlocal effect for fully simply supported and fully clamped edges with $\mu=4nm^2$ are found to be 51.83% and 75.55%, respectively.

4. 5. Effect of Elastic Medium  As the nano-plates are used as reinforcements in advanced nano-composites [3-5], an investigation on the effect of elastic medium on critical loads of a triangular nano-composite plate, in the presence of non-locality, is carried out in this section. Since the elastic matrix of nano-composite here is modeled using the two-parameter Winkler-Pasternak elastic medium, Equation (13), the effect of these parameters namely the Winkler parameter $k_w$ and the Pasternak parameter $k_p$ on critical buckling loads are studied and the results are presented in Figure 10a and Figure 10b, respectively. It is seen in Figure 10a that as the Winkler parameter increases the buckling loads increase for all values of nonlocal parameter. Also it is found in this figure that as the nonlocal parameter increases the current increase takes place in a nonlinear manner. The Pasternak parameter of the medium has the same influence on the buckling parameter as it can be seen in Figure 10b. However, here in the current domain of the Pasternak parameter, the increase in buckling parameter is linear. It is seen that the medium parameters affect the influence of nonlocal parameter on the results as was reported before [31].

To show this, error percent form of the results are presented in Figure 11a and 11b for Winkler and Pasternak parameters, respectively. It is found from Figure 11a that for nonlocal parameter $\mu=1 nm^2$ as the Winkler parameter increases the error percent decreases. This means that the increase in Winkler parameter of elastic medium, a harder matrix for nano-composite plate, decreases the nonlocal effect for the current value of nonlocal parameter. But for other nonlocal parameters the trend is somehow different. For example for nonlocal parameter $\mu=2 nm^2$ the error percent decreases by Winkler parameter until a special amount, here about $K_w=800$, then it increases with Winkler parameter. This can be interpreted so that as the medium become stiffer the nano-composite plate buckles in a different mode shape, a higher mode, and as the nonlocal effect is more prominent in the higher buckling modes, as discussed in section 4.2, the error percent increases.

![Figure 9. Effect of edges support and nonlocal parameter on buckling parameter](image)

![Figure 10. Effect of elastic medium and nonlocal parameter on critical buckling loads of isosceles triangular nano-composite plate: (a) Winkler parameter; (b) Pasternak parameter.](image)
Figure 11. Effect of elastic medium on the influence of nonlocal parameter on critical buckling loads of isosceles triangular nano-composite plate: (a) Winkler parameter; (b) Pasternak parameter.

In fact, the magnitude of Winkler parameter of elastic medium affects the buckling mode shape. Further, from Figure 11a it is revealed that as the nonlocal parameter increases this change in the error percent or change in buckling mode occurs for smaller Winkler parameters. For better understanding, the change in buckling mode shape with Winkler parameter is presented in Figure 12. From Figure 11b, also, it is found that as the Pasternak parameter increases the error percent and the nonlocal effect decrease. In fact, in the current domain for the Pasternak parameter the buckling mode shape is the same and the variation of error percent are smooth and linear. Thus, based on this interpretation the nonlinear manner in Figure 10a is also well understood. It should be noted that in Figures 10a, 10b, 11a and 11b the results are presented for non-dimensional medium parameters which are defined as:

\[ K_w = \frac{k_w a^4}{D_{11}}, \quad K_p = \frac{k_p a^4}{D_{11}}. \]  

(27)

5. CONCLUSION

In this work, buckling analysis of orthotropic triangular nano-composite plates under uniform in-plane compression at the nano scale has been studied using the nonlocal CPT. Based on the nonlocal theory, the governing equations for both vibration and buckling problems have been derived and the Galerkin method has been applied to solve the eigenvalue equations. Areal coordinates system has been employed to express the geometry of triangular nano-composite plate with arbitrary shape in a simple form, and then the interpolation functions have been used to form an assumed expression for the transverse displacement which also satisfies the kinematic boundary conditions at the edges. In the current solution method, there is no need for mesh generation and thus large degrees of freedoms. Effect of small scale for different base side lengths, mode numbers, aspect ratios, material parameters, boundary conditions and medium parameters has been investigated. From the study the following conclusions can be drawn:

- The small scale has a decreasing effect on the critical loads of isosceles and right-angled triangular nano-composite plates.
- Nonlocal effect becomes more prominent when the base side length of triangular nano-composite plate decreases.
- The small scale effect decreases when the aspect ratio increases.
- Non-locality has greater influence on critical loads in higher mode numbers.
- Buckling parameter increases by increasing degree of anisotropy and the difference between nonlocal and local results increases for greater values of anisotropy ratio.
The nonlocal effect is more prominent for clamped edges.

The Winkler parameter of elastic matrix increases the critical loads of triangular nano-composite plates but has different influences on the nonlocal effect i.e. it can decrease or increase the nonlocal effect depending on its value and the buckled shape of the nano-composite plate.

The Pasternak parameter of the medium increases the buckling loads of the triangular nano-composite plate and decreases the nonlocal effect both in linear manners.

Finally, it has to be mentioned that the solution procedure taken here can also be applied for the buckling analysis of nano-composite plates with arbitrary shape which is an efficiency for imperfect structures’ analysis and topology optimization problems in which other methods of studying such as experiment or molecular simulations may be impossible or lead to huge time lapses.

6. REFERENCE


\textbf{APPENDIX}

\[ \Pi(x,y) = D_{11}W_{xx}x_{xx} + D_{12}[W_{xx}x_{yy} + W_{yy}x_{xx}] + D_{22}W_{yy}x_{yy} + 4D_{33}W_{xx}x_{xx} \]

\[ + k_x \left[ W_{xx} + \mu \left( W_{xx,x} + W_{xx,y} \right) \right] + k_y \left[ W_{yy} + \mu \left( W_{yy,x} + W_{yy,y} \right) \right] \]

\[ - \alpha^2 \left[ m_0 \left( W_{xx} + \mu \left( W_{xx,x} + W_{xx,y} \right) \right) + m_y \left( W_{yy} + \mu \left( W_{yy,x} + W_{yy,y} \right) \right) \right] \]

\[ + N_{xx} \left[ W_{xx} + \mu \left( W_{xx,x} + W_{xx,y} \right) \right] + N_{yy} \left[ W_{yy} + \mu \left( W_{yy,x} + W_{yy,y} \right) \right] \]

\[ + N_y \left[ W_{yy} + \mu \left( W_{yy,x} + W_{yy,y} \right) \right] \] \hspace{1cm} \text{(A.1)}

\[ \lambda(s) = \int \left[ W_{xx} \left( D_{11} + \mu(k_p - m_2\alpha^2) + N_{xx} \right) n_j + W_{yy} \left( D_{12} + \mu(k_p - m_2\alpha^2) + N_{yy} \right) n_j \right] dxdy \]

\[ + 4D_{33} + \frac{\mu(k_p - m_2\alpha^2) + N_{xx} + 2N_{yy} n_j}{n_j} n_j + W_{yy} \left( D_{22} + \mu(k_p - m_2\alpha^2) + N_{yy} \right) n_j - W_j \left( k_p - m_2\alpha^2 \right) n_j \]

\[ + N_{yy} \left( k_p + m_2\alpha^2 \right) n_j - W_j \left( k_p - m_2\alpha^2 + N_{yy} \right) n_j + N_{xx} \left( k_p - m_2\alpha^2 + N_{xx} \right) n_j \]

\[ - \chi_{xx} \left( D_{11} + \mu(k_p - m_2\alpha^2 + N_{xx} + N_{yy} n_j) \right) n_j + W_{yy} \left( 4D_{33} + \mu(k_p - m_2\alpha^2 + N_{yy} + N_{yy} \left( k_p - m_2\alpha^2 \right) \right) n_j \]

\[ W_{yy} \left( D_{12} n_j \right) - \chi_{yy} \left( D_{22} + \mu(k_p - m_2\alpha^2 + N_{xx} n_j + N_{yy}) \right) n_j + \mu W_{yy} \left( k_p - m_2\alpha^2 + N_{yy} \right) n_j \]

\[ + N_{yy} n_j \right) \] \hspace{1cm} \text{(A.2)}

\[ K_\theta = \int \left[ D_{11} \frac{\partial^2 \Phi}{\partial x^2} \frac{\partial^2 \Phi}{\partial y^2} + D_{12} \left( \frac{\partial^2 \Phi}{\partial x^2} \frac{\partial^2 \Phi}{\partial y^2} + \frac{\partial^2 \Phi}{\partial x^2} \frac{\partial^2 \Phi}{\partial y^2} + 4D_{33} \frac{\partial^2 \Phi}{\partial x^2} \frac{\partial^2 \Phi}{\partial y^2} \right) \right] dxdy \] \hspace{1cm} \text{(A.3)}

\[ M_\theta = \int \left[ m_0 \left( \Phi \Phi + \mu \left( \frac{\partial \Phi}{\partial x} \Phi + \frac{\partial \Phi}{\partial y} \Phi \right) \right) \right] dxdy \] \hspace{1cm} \text{(A.4)}

\[ B_\theta = \int \left[ \frac{\partial \Phi}{\partial x} \Phi + \frac{\partial \Phi}{\partial y} \Phi \right] \left( \frac{\partial \Phi}{\partial x} \Phi + \frac{\partial \Phi}{\partial y} \Phi \right) dxdy \] \hspace{1cm} \text{(A.5)}
Nonlocal Effect on Buckling of Triangular Nano-composite Plates

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Department of Mechanical Engineering, University of Jiroft, Jiroft, Iran

Abstract

In this study, the small-scale effect on the buckling behavior of triangular nanocomposite plates under uniform pressure is investigated. Since the small-scale effect is prevalent in the nano-structure, the nonlocal elasticity theory is used to develop an equivalent continuous model for nanocomposites by considering the change in their mechanical behavior. For the boundary conditions of the triangular nanocomposite plate, the classical plate theory and virtual work principle are used. The governing equations are derived by the Galerkin method using a coordinate system as the basis. The solution of the present study is considered as an infinite plate with an arbitrary shape. The effects of non-local parameters, plate dimensions, aspect ratio, buckling modes, imperfections, supports at the edges, and the elastic matrix parameters are studied. The results show that all these parameters significantly affect the nanocomposite plate's stability characteristics. The results show that the non-local parameter, especially in small dimensions, lower aspect ratio, higher buckling modes, larger imperfections, and stronger supports, plays a significant role. Moreover, the results show that the elastic matrix parameters, especially the Winkler parameter, can significantly affect the small-scale effect and can lead to decreases or increases. The use of the classical elasticity theory can lead to significant overestimations of the buckling load, which can be used in the design and analysis of these structures. The results of this study can be used in the design, analysis, and optimization of many nanosystems such as electronic-mechanical nanosystems using nanocomposite plates as parts. It is shown that the nanocomposite plates can increase the overall stiffness of nanosystems, but in this study, it is shown that the small-scale effect in nanosystems, especially in the triangular nanocomposite plates, can significantly decrease the buckling load. Therefore, the small-scale effect plays a significant role in the design and analysis of these structures and should be considered accurately.