A MATHEMATICAL MODEL FOR BLOOD FLOW THROUGH NARROW VESSELS WITH MILD-STENOSIS

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Abstract In this paper we examine the effect of mild stenosis on blood flow, in an irregular axisymmetric artery with oscillating pressure gradient. The Herschel-Bulkley fluid model has been utilized for this study. The combined influence of an asymmetric shape and surface irregularities of constriction has been explored in this computational study. An extensive quantitative analysis has been performed for narrowing of vessels through numerical computations on the flow velocity, plug flow rate and the apparent fluidity. The graphical representations have been made to validate the analytical findings with a view of its applicability to stenotic diseases. Velocity profiles, plug flow rate, and apparent fluidity along the radius of the obstructed tube are determined to give the flow characteristics, for diagnostic point of view. The effects of viscosity on the flow field are examined numerically and are shown graphically.

Keywords Mathematical Model, Mild-Stenosis, Micropolar Fluid, Shearing Stress, Apparent Fluidity

1. INTRODUCTION

It is known that a severe constriction of a coronary artery significantly alters the mean resting coronary flow. Cardiac ischemia is caused due to the constriction, which is responsible for insufficient flow of blood through the coronary arteries into the heart. This insufficiency is usually caused by atherosclerotic plaque, which builds up in the coronary arteries, gradually diminishing the flow of blood through the said arteries. Such occlusion of the arteries increases the risk of heart attack. Therefore the study of blood flow in artery is quite important. However, there have been limited studies of the effects of fluid dynamics on a stenosis in artery using proper modeling techniques (Cavalcanti, et al [1]). At low flow rates stenotic resistance (ratio of pressure drop to flow) is essentially constant, and this suggests fully developed laminar flow (Misra, et al [2]). In the case of high flow, resistance increases with the flow, indicating the importance of turbulence flow effects. It was further observed by researchers, that the resistance of the stenosis was primarily
dependent on its minimum cross-sectional area rather than its length (Chakravarty, et al [3]). These types of studies have been confounded to a description of the overall behavior of blood flow in the presence of a stenosis through experimental investigation.

Analytical models also have been developed in an effort to predict the pressure drop, caused by a given stenotic area. The minimum lumen areas created in stenosed tube were about 65% and 90%, including a model without stenosis, respectively (Zohdi, et al [4]). Ischemic heart disease, which results from high grade stenosis, is the single most common cause of death all over the world. Approximately 35 percent of all deaths are resulted by this cause. High grade stenosis increases flow resistance in arteries, which forces the body to raise the blood pressure in order to maintain the necessary blood supply. Both high pressure and narrowing vessels cause high flow velocity, high shear stress and low or even negative pressure, at the throat of the stenosis (Wille, et al [5]). These may be related to thrombus formation, atherosclerosis growth and plaque cap rupture, leads directly to stroke and heart attack. The exact mechanism of this complicated process is still not well understood. A more comprehensive study in this physiological process is of great importance for diagnosis, prevention and treatment of stenosis related diseases. A considerable number of experimental and numerical researches have been conducted to study the flow dynamics and stresses in collapsible elastic tube (Tang, et al [6]).


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While much work has been reported, the mathematical models for flow in stenotic collapsible tubes were primarily limited. But, most researches were focused on elastic tubes, in which stress, produces its characteristic strain instantaneously, and strain vanishes immediately upon the removal of the stress. In fact for realistic modeling channels have been considered porous as in human physiological tissues in the arteries such the nutrients flowing within the blood. All the above studies are devoted in the wake of the new models for blood flow over the stenosis. Modeling of blood flow over the mild stenosis with medium degree of constriction through Herschel-Bulkley fluid model for blood flow with oscillating pressure gradient is considered in the present study. Further more we consider blood as non-Newtonian fluid. The rest of the paper is organized in various sections as follows. In Section 2, we describe the basic model with assumed notations, which are used for mathematical formulation purpose. In Section 3, we explore the design parameters for numerical illustration. The variation of viscosity, shearing stress and velocity over the stenosis are also explained, descriptively as well as graphically. Finally, the conclusions are drawn in the Section 4.

2. MODEL DESCRIPTION

We consider axisymmetric steady flow in a mild stenotic tube. The flow is assumed to be laminar, non-Newtonian, viscous and incompressible. The shape of the tube is under zero pressure and the tube wall is assumed to have no axial motion, that is, no slipping takes place between the fluid and the wall. The pressure gradient is oscillatory in nature, which is compatible with a pumping heart motion. The complex nature of blood with various parameters is approximated here. The blood is in a uniform circular tube with an axisymmetric mild stenosis takes place whose boundary is specified by Krogh model, (Kapoor, et al [13]);

\[
\frac{R}{R_0} = 1 - \frac{\delta}{2R_0} \left(1 + \cos \frac{2\pi}{L_0} \right) ; \frac{L_0}{2}, \frac{L_0}{2} \\
(z - d - \frac{L_0}{2}) ; \frac{L_0}{2} \leq z \leq L_0 + d
\]

Where \( R_0 \) is the radius of unobstructed tube and \( R \) is the radius of obstructed tube. \( L_0 \) is the length of the stenosis and \( d \) is the location of the stenosis. The maximum height of stenotic growth is taken as \( \delta \). The schematic diagram is shown in Figure 1.

\[
\nabla \cdot \mathbf{V} = 0
\]

The momentum equation of motion is

![Figure 1. Schematic diagram of a mild-stenotic tube equation of continuity.](image)
\[
\rho \frac{Dv}{Dt} = -\nabla p + \nabla \cdot \tau \tag{3}
\]

Where \( \rho \) is the density, \( p \) is the pressure, and \( \tau \) is the shearing stress tensor.

Herschel-Bulkley law to model the fluid behavior of blood flow, taking into account two characteristic features, which has emerged from the experimental data namely:

- The presence of a yield stress,
- The dependence of the viscosity with respect to the shear rate. (see. ref. Kapoor, et al [13])

Let \( \tau_0 \) be the yield stress, the coefficient of viscosity is \( \mu \) and \( \gamma' \) be the strain rate.

Then constitutive equation in one dimensional form for Herschel-Bulkley pulsatile fluid with the shearing stress \( \tau \), is given by

\[
\tau = \mu (\gamma')^n + \tau_0, \quad \tau \geq \tau_0
\]
\[
\gamma' = 0, \quad \tau < \tau_0 \quad \text{(see. ref. Tu, et al [31])} \tag{4}
\]

The governing equation of motion for steady incompressible blood flow with pressure gradient through the mild stenosis in an artery reduces to the following form:

\[
-P = \frac{1}{r} \frac{\partial}{\partial r} \left( r \tau \right) \tag{5}
\]

Where,

\[
\frac{\partial p}{\partial z} = -p, \tag{6}
\]

\( P \) being a constant. Integrating Equation 5 with respect to \( r \) which is the radial co-ordinate, we have

\[
\tau = -P \frac{r}{2} \tag{7}
\]

From Equations 4 and 7, we have

\[
- \left( \frac{P}{\mu} \frac{r}{2} + \frac{\tau_0}{\mu} \right) = (\gamma')^n \tag{8}
\]

For the Herschel-Bulkley fluid in circular tube, we have \( \gamma' = 0 \) when \( \tau \leq \tau_0 \) and there is a core region which flows as a plug.

Let the radius of this plug region be \( r_p \). At the surface of this plug, the stress is \( \tau_0 \), so that considering the force on the plug, we get

\[
P \times \pi r_p^2 = \tau_0 \times 2\pi r_p
\]

or

\[
P \times r_p = 2\tau_0 \tag{9}
\]

Then Equation 8 becomes as

\[
(\gamma')^n = -\left( \frac{1}{2} \frac{P r}{\mu} + \frac{1}{2} \frac{P r_p}{\mu} \right)
\]

We know that

\[
\frac{dv}{dr} = \gamma' \tag{11}
\]

Then Equation 10 to

\[
\frac{dv}{dr} = -\left( \frac{1}{2} \frac{P r}{\mu} \right)^n (-r - r_p)^n
\]

The relevant conditions are

\[
v = 0, \text{ at } r = R \text{ and } R_0 \tag{13}
\]

Integrating (10) and using conditions (13), we get

\[
v = n \left( \frac{1}{2} \frac{P R}{\mu} \right)^n \frac{1}{n+1} (1+\beta) \frac{1+n}{n} \left( \frac{r}{R} \right) \}

Where

\[
\frac{r_p}{R} = \beta \tag{15}
\]

The real part on right hand side contributes to the fluid velocity.
Plug flow exists whenever the shear stress does not exceed yield stress. The velocity of the plug flow can be obtained by putting

\[ r = \beta R \]  
(16)

Then we get

\[ v_p = \frac{n}{n+1} \left( \frac{1}{2\mu} \right)^n (-R)^{1+n} \left( 1 + \frac{1}{n} \right) \left( 1 + \frac{n}{n+1} \right)^{1+n} \]  
(17)

Flow rate \( Q \) is obtained as follows:

\[ Q = \frac{n \pi}{3n+1} \left( \frac{1}{2\mu} \right)^n c^3 \left( 1 - \frac{3n+1}{n(2n+1)} \beta \right) \]  
(18)

Where

\[ c = (-R)^{1/n} \]  
(19)

Apparent fluidity \( \phi_a \) at maximum height of stenosis i.e. at \( Z = L_0/2 \) is obtained as follows:

\[ \phi_a = \left( \frac{1}{\mu} \right)^2 (1 - 3n) \left( \frac{\delta}{c} \right) (1 - \frac{3n+1}{2n+1} \beta) \]  
(20)

From Equation 16, we get the shear stress \( \tau_\omega \) as follows:

\[ \tau_\omega = \left( \frac{3n+1}{n \pi c^3} \right)^n (1 + 3n) \left( \frac{\delta}{c} \right) (1 + \frac{3n+1}{2n+1} \beta) \]  
(21)

3. NUMERICAL ILLUSTRATION

In this section, we present the numerical results for velocity profiles, volume flow rate, apparent fluidity and walls' shear stress. All these profiles provide detailed description of flow field. In the presence of mild-stenosis the flow exhibits a resistance and increases the shear stress. These are the quantities of physiological relevance. The computation was programmed by MATLAB 6.5 software and run on P-IV for default parameter values \( \beta = 1.29; r_0 = 0.01; \tau_\omega = 0.02; n = 2; r = 0.15; r_p = 0.003; P = 0.5; \) and \( \delta = 0.2 \). These values have been chosen in consultation with medical practitioner having long clinical experience.

Figure 2 depicts the velocity profiles of fluid flow with respect to the radius of the obstructed tube for different value of \( \mu \). It is observed that the velocity of fluid decreases with increasing \( r \) in the presence of mild-stenosis. Also as we increase the values of \( \mu \), the velocity decreases. In Figure 3, we see the trend of flow rate in the plug region for different values of \( \mu \). It is observed that the velocity in plug region increases gradually at first and then it becomes rapid with the increase in \( r \); by increasing the values of \( \mu \) the flow rate decreases. For different values of \( \mu \), the pattern of the apparent fluidity in the direction of radius is shown in Figure 4. It is seen that the apparent fluidity slightly increases first with \( r \) and then attains almost constant value. The findings are quite close to the experimental results (Cuniberti, et al [33]) done on rabbit.

4. CONCLUSION

A mathematical model of blood flow through an irregular arterial mild-stenosis is developed. The numerical simulation shows that the shape of the velocity is strongly perturbed by the stenosis and disturbances are clearly evident. The flow of blood is sharper for narrowing constricted channel. It is realized that if the viscosity of fluid increases, the velocity of fluid decreases in the presence of stenosis, which is desirable in the physical situation. If we put \( n = 0 \) our results tally with those of Zohdi, et al [4]. The reported results provide a coherent explanation of the critical role of hemodynamic factors, which are in agreement with the previous mathematical studies and physical situation. Our investigation may be helpful to medical practitioners to understand the blood flow in human cardiovascular system when one or more blood vessels are affected by stenosis. Computational results show how blood flow through various parts of the cardiovascular system may be affected by stenosis in different blood
vessels. The long-term application of our mathematical model is to provide the quantitative tool for gaining insights into the pathology of arterial diseases.

6. REFERENCES


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